## aselsan

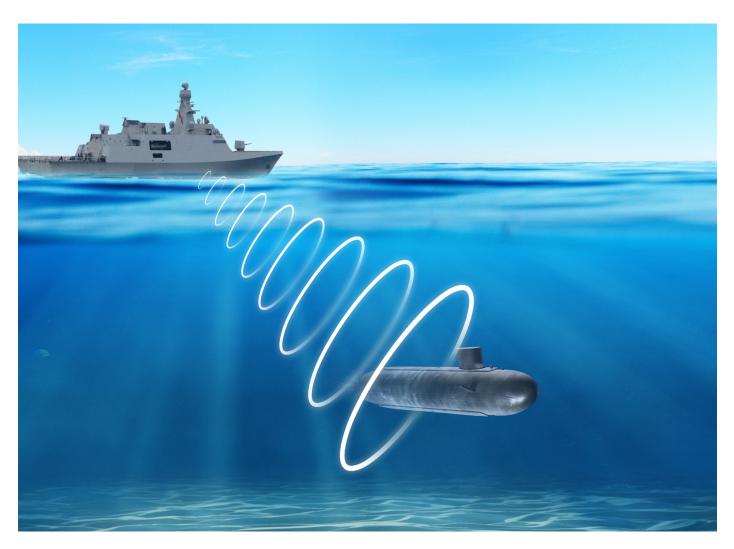


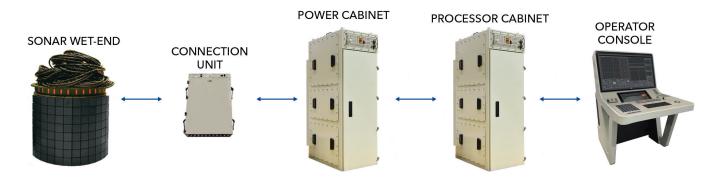
# **FERSAH**

### HULL MOUNTED ASW SONAR

ASELSAN FERSAH Hull Mounted ASW Sonar is a mid-frequency anti-submarine sonar with high source level and array directivity. The system has active and passive ASW modes, in addition to its Mine Like Object Avoidance (MAS) mode.

ASELSAN FERSAH Hull Mounted ASW Sonar has detection, tracking and analysis capabilities both in active and passive modes with state of the art signal processing techniques.





## **FERSAH**

#### Hull Mounted ASW Sonar

#### **System Configuration**

ASELSAN FERSAH Hull Mounted ASW Sonar consists of 5 units which are Sonar Wet-End, Connection Unit, Power Cabinet, Processor Cabinet and Operator Console.

Sonar Wet-End is used for transmission/reception (T/R) of the acoustical signals to/from the environment. It is composed of 36 stayes that are arranged in cylindrical fashion.

Connection Unit is used for analog connection between Sonar Wet-End and Processor Cabinet.

Power Cabinet includes high power voltage supplies.

Processor Cabinet includes signal processing algorithms, signal processing software, power amplifier electronics, front-end conditioning filter, preamplifiers and analog-digital converter (ADC) electronics.

Operator Console is the human machine interface of ASELSAN FERSAH Hull Mounted ASW Sonar. It consists of workstation, display, keyboard, programmable display keys, speaker and headset with microphone

#### **Environmental Conditions**

#### Sonar Wet-End

High Storage Temperature Low Storage Temperature High Operating Temperature Low Operating Temperature Shock IP Proof

MIL-STD-810F, Method 501.4, Procedure I MIL-STD-810F, Method 502.4, Procedure I MIL-STD-810F, Method 501.4, Procedure II MIL-STD-810F, Method 502.4, Procedure II MIL-S-901 D Shipboard Shock Test Grade-B

MIL-STD-810F, Method 501.4, Procedure I

MIL-STD-810F, Method 502.4, Procedure I

#### Sonar Dry-End (Except Operator Console)

High Storage Temperature Low Storage Temperature High Operating Temperature Low Operating Temperature Humidity Vibration

IP Proof

MIL-STD-810F, Method 501.4, Procedure II MIL-STD-810F, Method 502.4, Procedure II MIL-STD-810F, 507.4 MIL-STD-810F, Method 514.5, Procedure I MIL-STD-810F, 516.5 Shock EMI/EMC MIL-STD-461E

#### **Technical Specifications**

- Detection and tracking of 32 targets in active mode
- Detection and tracking of 8 targets in passive mode
- Horizontal Coverage
  - ASW Mode: 360°
  - MAS Mode: 90°
  - Active Sonar Frequency: 6.7 kHz, 7.5 kHz and 8.4 kHz
- Active Sonar ASW Mode: OMNI, SRDT, ARDT, TRDT, MCC
- Passive Sonar Frequency Band: 3 kHz 12 kHz
- Pulse Type: CW, FM and COMBO (CW+FM)
- Pulse Lenath
  - CW: 16, 64, 128, 256 ms
  - FM: 8, 16, 64, 128, 256 ms
- Range Scale: 2250, 4500, 9000, 18000, 36000 m
- Electrical Supply Voltage
  - Processor Cabinet: 115 VAC, 60 Hz, phase 1
  - Power Cabinet: 115 VAC, 60 Hz, 1φ and 440 VAC, 60 Hz, phase 3
  - Operator Console: 115 VAC, 60 Hz, phase 1
  - Connection Unit: 115 VAC, 60 Hz, phase 1

#### **General Specifications**

- Open architecture and modular design
- Modern signal processing algorithms
- Modern human machine interface
- Onboard training simulator
- Rugged design
- Compatibility with military standards
- Standalone working capability
- Integration to Combat Management System
- Capability of Built-in Test (BIT)
- Water cooling cabinet structure
- Recording acoustic data
- Data transfer to portable storage devices.
- **Dummy Load Electronics**
- Raw Data Recording and Replay
- Self Noise Monitoring and Recording
- Screenshot/Video Recording and Replay
- Printing Capability



IP23